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Exercise 1 *GMM and the Three Tests*

The hardest part is to get a stable estimate for both the unrestricted and the restricted version. We do this in six steps.

- 1) We find unrestricted $\beta^{(1)}$ using an identity weight matrix and "fminsearch".
- 2) Given that, we compute the optimal weight matrix $V^{(2)}$ and find the corresponding $\beta^{(2)}$.
- 3) We Repeat step 2 and obtain $V^{(3)}$ and the corresponding $\beta^{(3)}$.
- 4) We Compute A and $m_n(\beta^{(3)})$.
- 5) We find restricted $\beta^{(5)}$ using $V^{(3)}$ as the weight and "fmincon".
- 6) We compute $m_n(\beta^{(5)})$ and $V^{(5)}$.

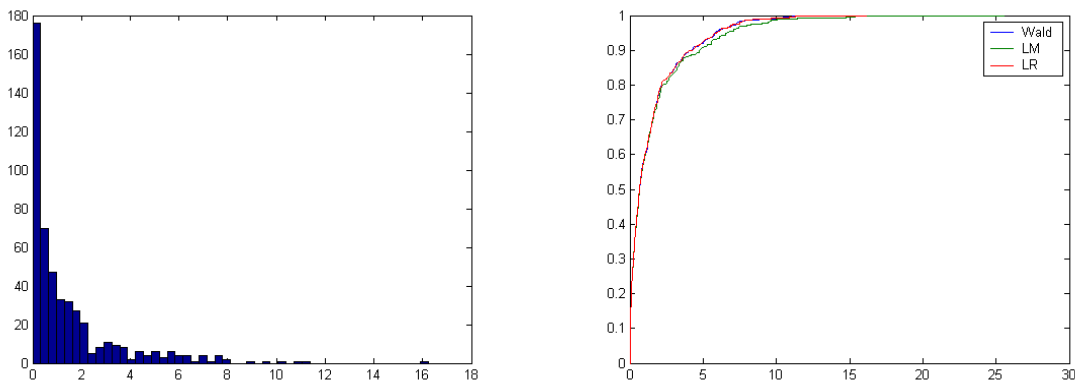
After that we calculate the three tests: $W = nr' \left(R \left(A \left(V^{(3)} \right)^{-1} A' \right)^{-1} R' \right) r$,

$$LM = nm_n(\beta^{(5)})' \left(V^{(3)} \right)^{-1} A' \left(A \left(V^{(5)} \right)^{-1} A' \right)^{-1} A \left(V^{(3)} \right)^{-1} m_n(\beta^{(5)}),$$

$$LR = n \left(m_n(\beta^{(5)})' \left(V^{(3)} \right)^{-1} m_n(\beta^{(5)}) - m_n(\beta^{(3)})' \left(V^{(3)} \right)^{-1} m_n(\beta^{(3)}) \right),$$

where $r = \beta_2\beta_3 + \beta_4$, $R = [0, \beta_3, \beta_2, 1]$.

The reason why we use $V^{(3)}$ is because it is the weight matrix, we used when finding the minimum - the one we regard as 'optimal'. Besides, otherwise we often get negative values for the LR test. The whole procedure is very sensitive to $V^{(3)}$, that's why we repeated the second step, to be sure we are getting a good estimate of the 'optimal' weight matrix.



The histograms are almost identical: one of them is depicted on the left. The graph on the right compares the three empirical c.d.f.'s of the tests. They are almost indistinguishable. The probabilities of type I errors for the 95% level are all around 11-12%. The means differ a little, which can be clearly seen in the graph.

	Wald	LM	LR
mean	1.47	1.62	1.47
median	0.67	0.67	0.66
P(type I error)	0.109	0.118	0.108

Exercise 2 *NLLS as an Example of GMM*

$$y_i = g(x_i, \theta_0) + u_i \quad E(u_i|x_i) = 0$$

1) $E[(y_i - g(x_i, \theta))^2] \rightarrow \min_{\theta}$ use law of iterated expectations:

$$\text{FOC: } E\left[2\frac{\partial}{\partial\theta}g(x_i, \theta)(y_i - g(x_i, \theta))\right] = E\left[2\frac{\partial}{\partial\theta}g(x_i, \theta)E[(y_i - g(x_i, \theta))|x_i]\right] = 0$$

$$\text{since } E(u_i|x_i) = 0 \Leftrightarrow E(y_i|x_i) = g(x_i, \theta_0), \quad E\left[2\frac{\partial}{\partial\theta}g(x_i, \theta)(g(x_i, \theta_0) - g(x_i, \theta))\right] = 0$$

If $g(\cdot)$ is strictly monotone in θ , this expression is satisfied iff $\theta = \theta_0$.

2) The usual conditions for existence are continuity of $g(\cdot)$ and compactness of Θ . For uniqueness we need to add: $\theta \neq \theta_0 \Rightarrow g(x, \theta) \neq g(x, \theta_0)$. Strict monotonicity in θ is one possibility.

$$3) \hat{\theta}_n = \arg \min_{\theta} m_n(\theta)' (V_n)^{-1} m_n(\theta)$$

$$m_n(\theta) = \frac{1}{n} \sum \varphi(y_i, x_i, \theta) \quad \varphi(y_i, x_i, \theta) = z(y_i - g(x_i, \theta))$$

Some simple ideas for instruments z_{ji} include: $1, x_{1i}, \dots, x_{Ki}$.

4) Some additional simple ideas for instruments z_{ji} include: $x_{1i}^2, \dots, x_{Ki}^2$.

We can use higher powers, if needed. The justification to that would be a Taylor expansion of $\frac{\partial}{\partial\theta}g(x_i, \theta)$ around θ_0 . These are all instruments since $E[f(x_i)(y_i - g(x_i, \theta))] = 0$ only in θ_0 .

5) An optimal GMM estimator uses an optimal weight matrix:

$$\hat{V}_n = \frac{1}{n} \sum \varphi(y_i, x_i, z, \hat{\theta}') \varphi(y_i, x_i, z, \hat{\theta}')'$$

Can use any consistent $\hat{\theta}'$, e.g. $\hat{\theta}' = \arg \min_{\theta} m_n(\theta)' m_n(\theta)$.

6) Asymptotic distribution: $\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{d} N(0, \Lambda(\theta_0))$, where

$$A(\theta_0) = E_0 \left[\frac{\partial \varphi(y, x, z, \theta_0)}{\partial \theta} \right], \quad V(\theta_0) = E_0 [\varphi(y, x, z, \theta_0) \varphi(y, x, z, \theta_0)']$$

$$\Lambda(\beta_0) = (A(\theta_0) V(\theta_0)^{-1} A(\theta_0)')^{-1}$$

A consistent estimator for $A(\theta_0)$ is $\hat{A} = \sum \frac{\partial \varphi(y_i, x_i, z_i, \hat{\theta}')}{n \partial \beta}$

A consistent estimator for $V(\theta_0)$ is $\hat{V}_n = \frac{1}{n} \sum z_i z_i' (y_i - x_i' \hat{\theta}')^2$ - non-singular, p.s.d.

Proof is exactly the same as always.

7) $H_0 : \theta_1 \theta_2 \dots \theta_K = 1$ $H_1 : \theta_1 \theta_2 \dots \theta_K \neq 1$

$$r(\theta) = \theta_1 \theta_2 \dots \theta_K - 1 \quad R(\theta) = [\theta_2 \dots \theta_K, \theta_1 \theta_3 \dots \theta_K, \dots, \theta_1 \theta_2 \dots \theta_{K-1}]$$

$$\tilde{\theta}_n = \arg \min_{\theta} m_n(\theta)' (\tilde{V}_n)^{-1} m_n(\theta) \text{ s.t. } r(\theta) = 0 \quad \tilde{A} = \sum \frac{\partial \varphi(y_i, x_i, z_i, \tilde{\theta}')}{n \partial \beta}$$

$$\tilde{V}_n = \frac{1}{n} \sum \varphi(y_i, x_i, z_j, \tilde{\theta}') \varphi(y_i, x_i, z_i, \tilde{\theta}')', \quad \tilde{\theta}' = \arg \min_{\theta} m_n(\theta)' m_n(\theta) \text{ s.t. } r(\theta) = 0$$

$$W = nr(\hat{\theta})' \left(R(\hat{\theta}) \left(\hat{A}(\hat{V})^{-1} \hat{A}' \right)^{-1} R(\hat{\theta})' \right) r(\hat{\theta}),$$

$$LM = nm(\tilde{\theta})' (\tilde{V})^{-1} \tilde{A}' \left(\tilde{A}(\tilde{V})^{-1} \tilde{A}' \right)^{-1} \tilde{A}(\tilde{V})^{-1} m(\tilde{\theta}),$$

$$LR = n \left(m(\tilde{\theta})' (\tilde{V})^{-1} m(\tilde{\theta}) - m(\tilde{\theta})' (\tilde{V})^{-1} m(\tilde{\theta}) \right) \quad \text{All distributed as } \chi^2(1).$$